

ANIE
AUTOMAZIONE



Automated Guided Vehicles, contactless transport systems

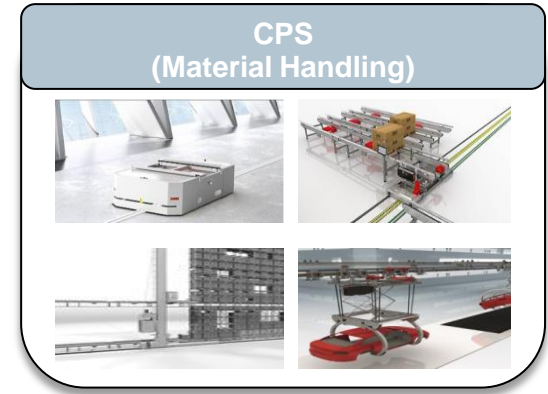
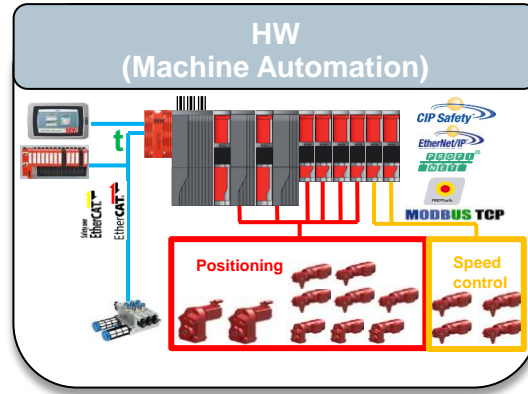
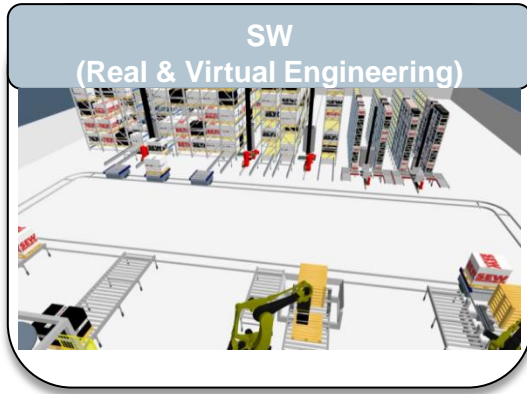
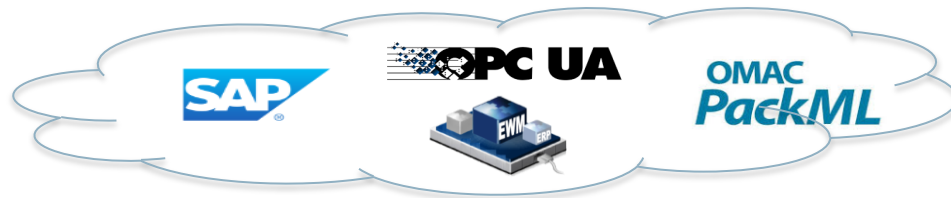
Mr. Franco Zannella



Mr. Antonello Lauriello



Industry 4.0: Smart factory

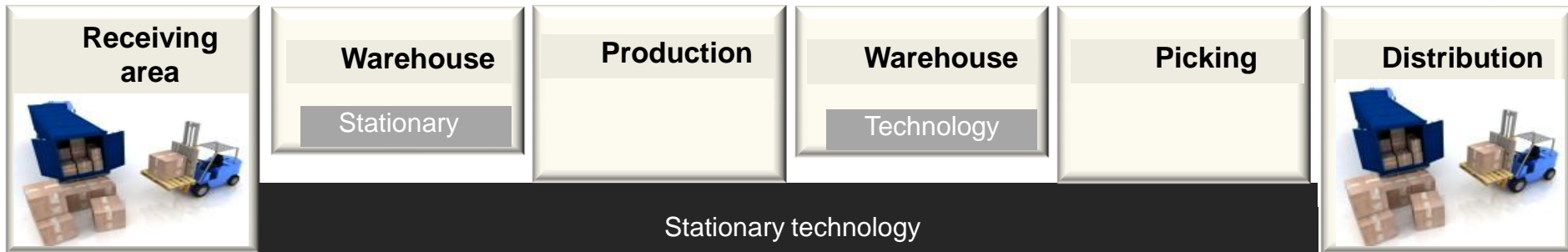


+ Flexibility (Product Mix, Volume Mix)
+ Productivity (Uptime, Efficiency, Quality O.E.E.)

+ Energy Saving (Green label, regenerative)
+ Operating efficiency (TCO, Engineering, Maintenance)

The factory of today

- Production is oriented on throughput
- Mass production, no customized products
- Long changeover time for production of new products on the same line
- Stationary conveyor technology for in-plant logistics

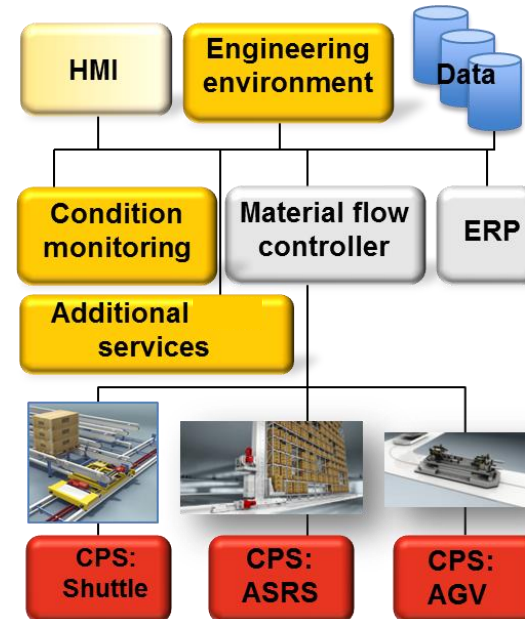


But: More and more flexibility and customized products are needed.
How can production be adapted?

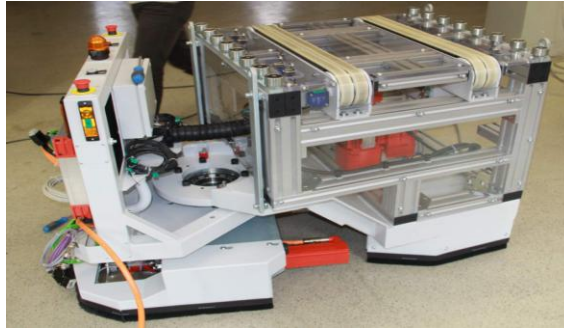


The factory of the future (2018 →)

- Production is oriented on different incoming order, with different and customized product “One Piece Flow”.
- The machines can be quickly adapted and in a flexible way, for the different products needs to be produced.
- Mobile technology and logistic assistant are working inside all productive area of the facility, included warehouse



How to get this flexibility ?



Inductive power supply contactless

Efficient in operation

contactless supply system, maintenance free, high protection class, simple installation, modular system, flat pick-up

Supply unit

- 4 kW / 16 kW (for panel installation)
- Line cable current 85 A (25 kHz)

Pick-up

- 1.5 kW to 3,6 kW
- Overload capability for the supply units and for the pick-ups THM20E



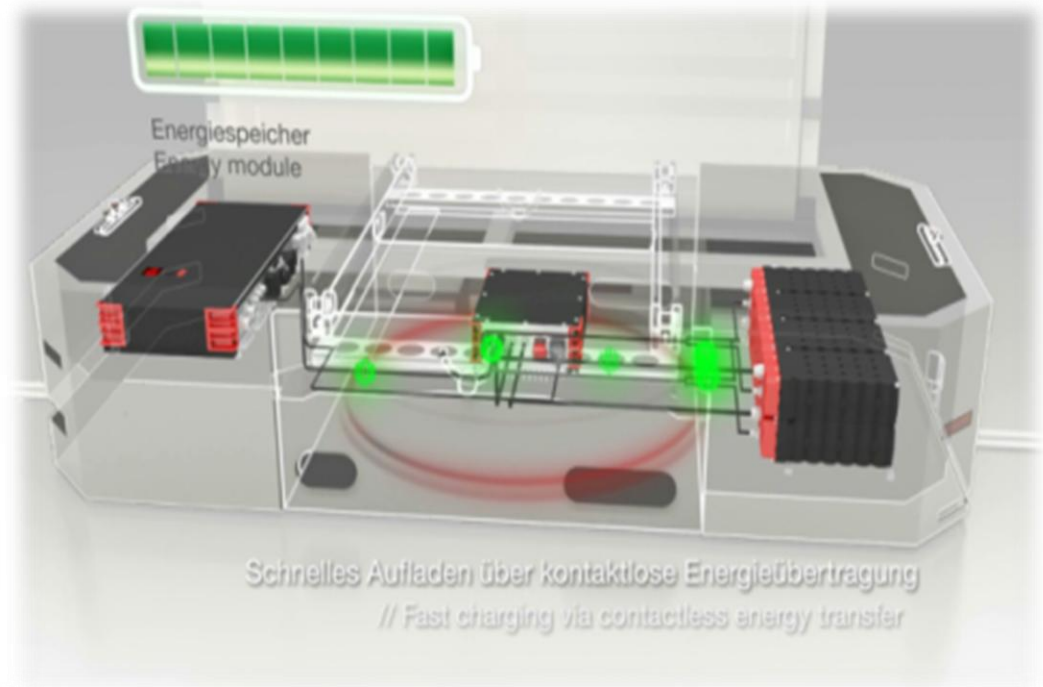
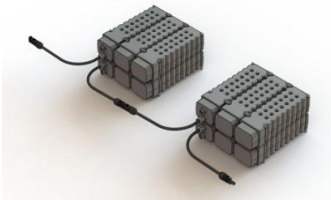
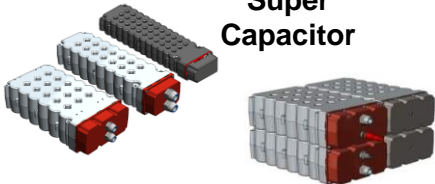
Energy buffer for AGV:

Hybrid system with Super Capacitor for energy management

Energy buffer management.

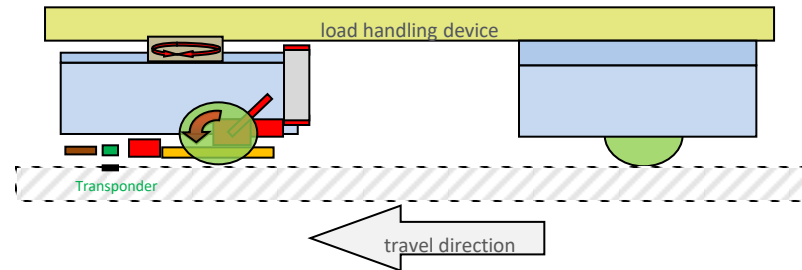
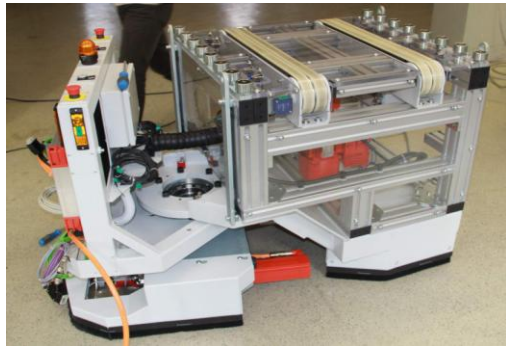
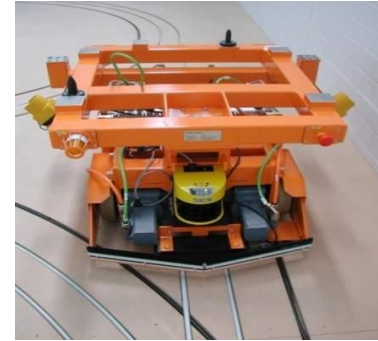
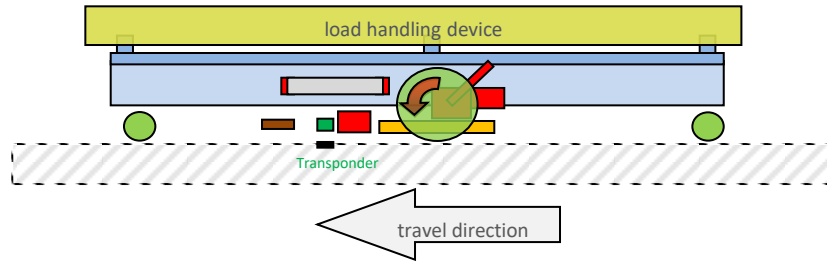


Super Capacitor

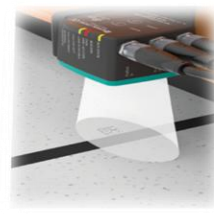
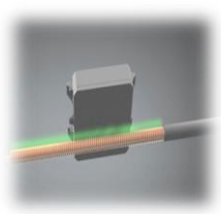
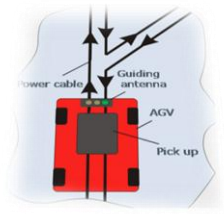
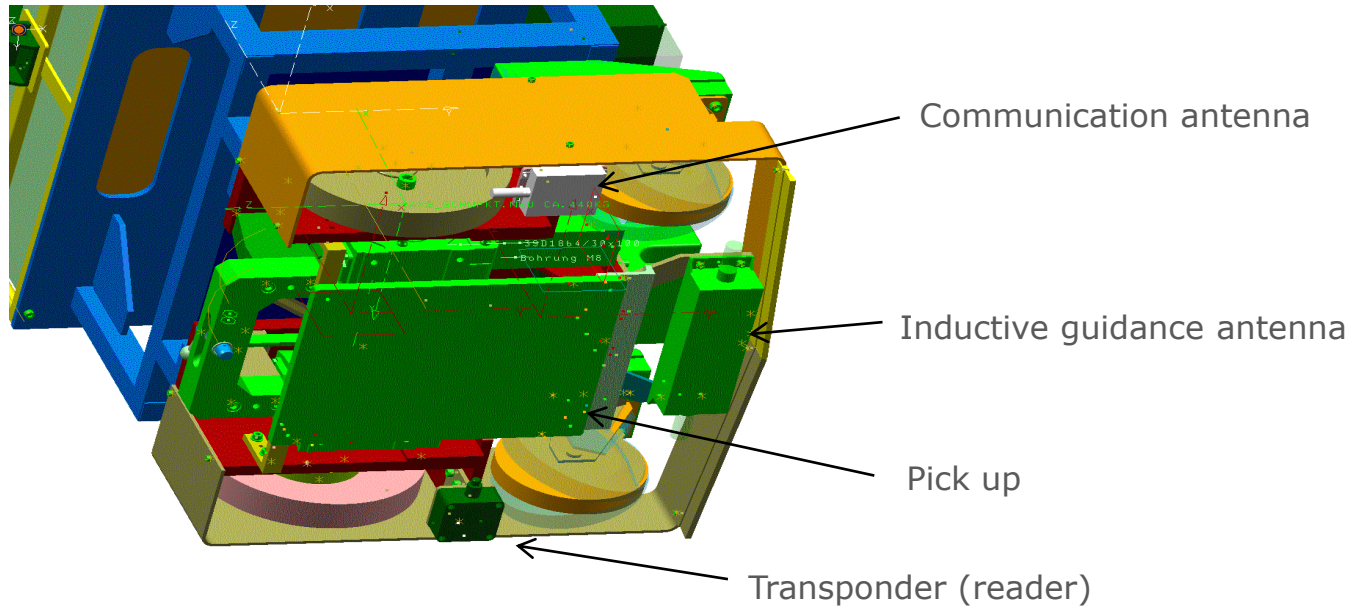


Mechanical characteristic of the vehicle AGV

The vehicle's mechanical configuration changes with the application

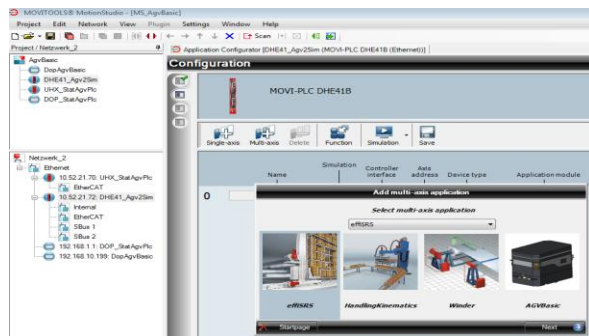


AGV positioning component lower side

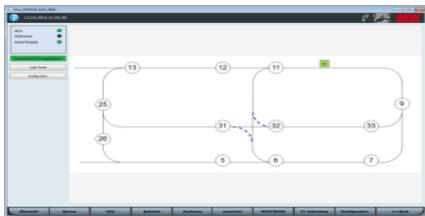


The software framework:

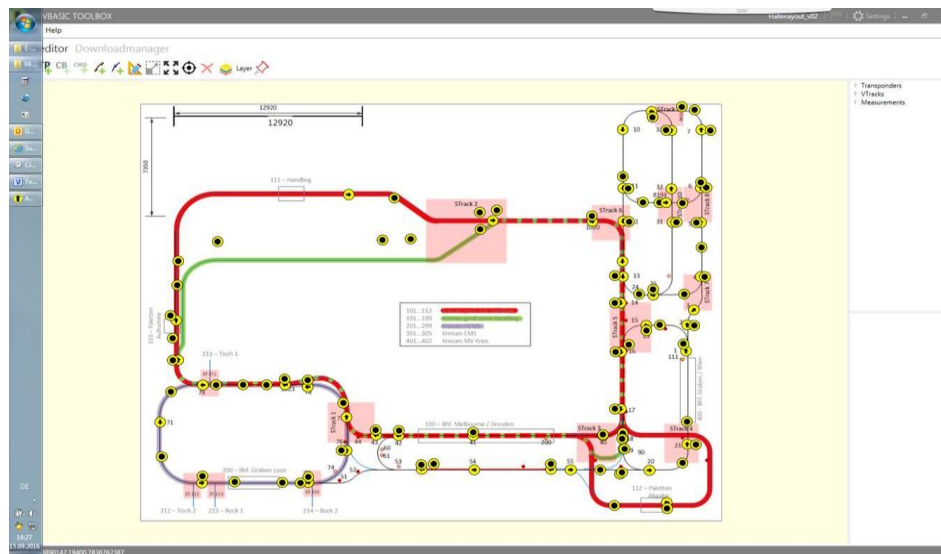
Flexible and easy sw



AGV parametrization



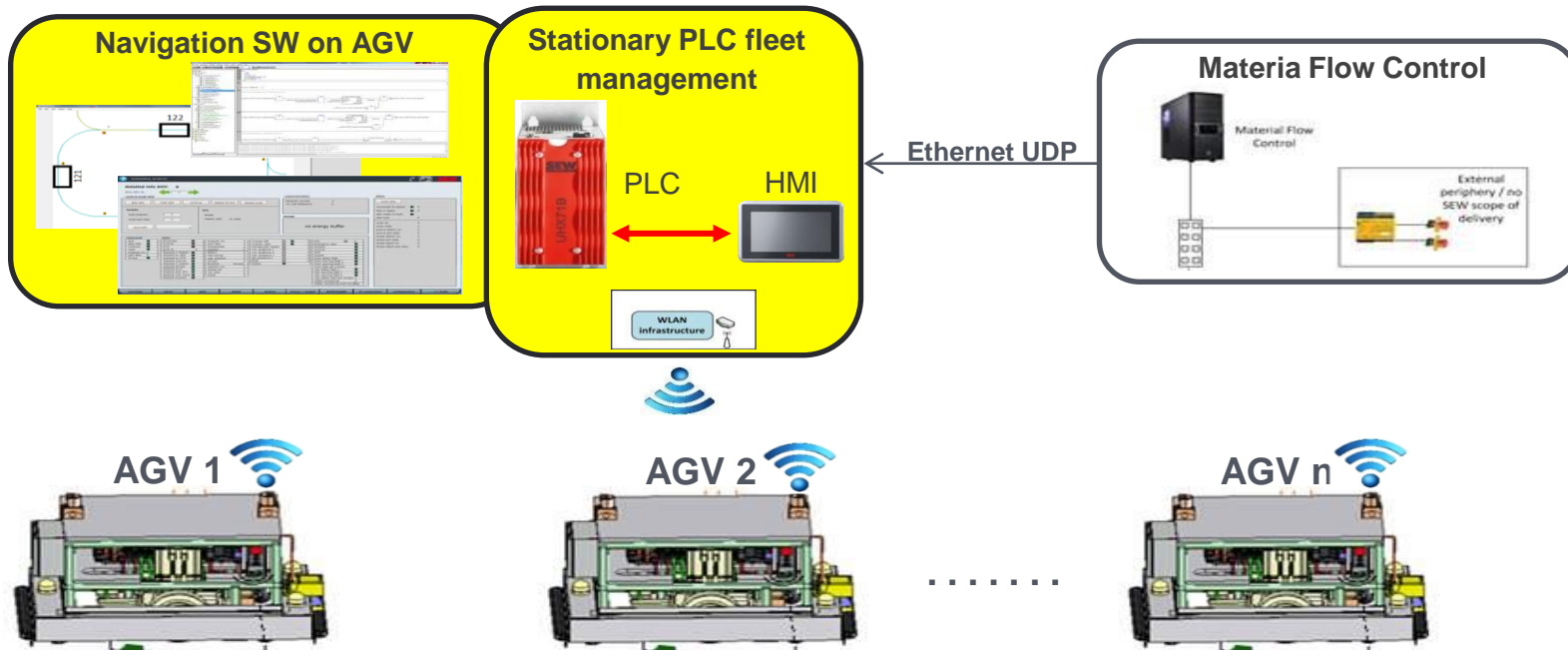
Track designer



Process emulator

Higher system fleet management:

Fleet coordination by stationary plc



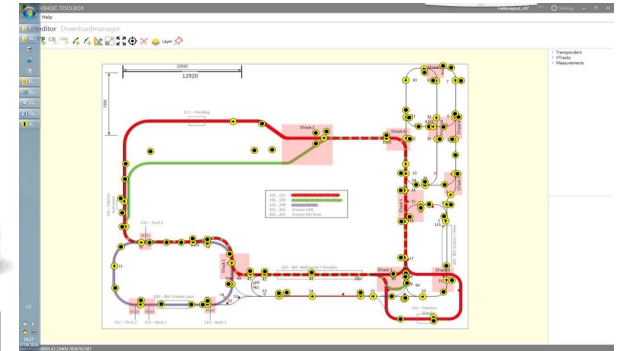
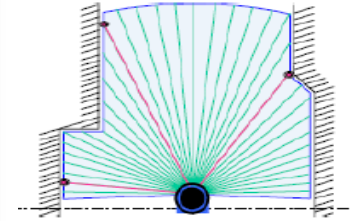
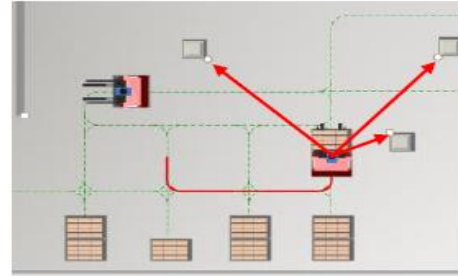
Laser Guided Vehicles:

Principle:

- Reflector data will be detected by the laser scanner
- Reflector data (distance and angle) will be measured and are the basis for position calculation

SW Architecture:

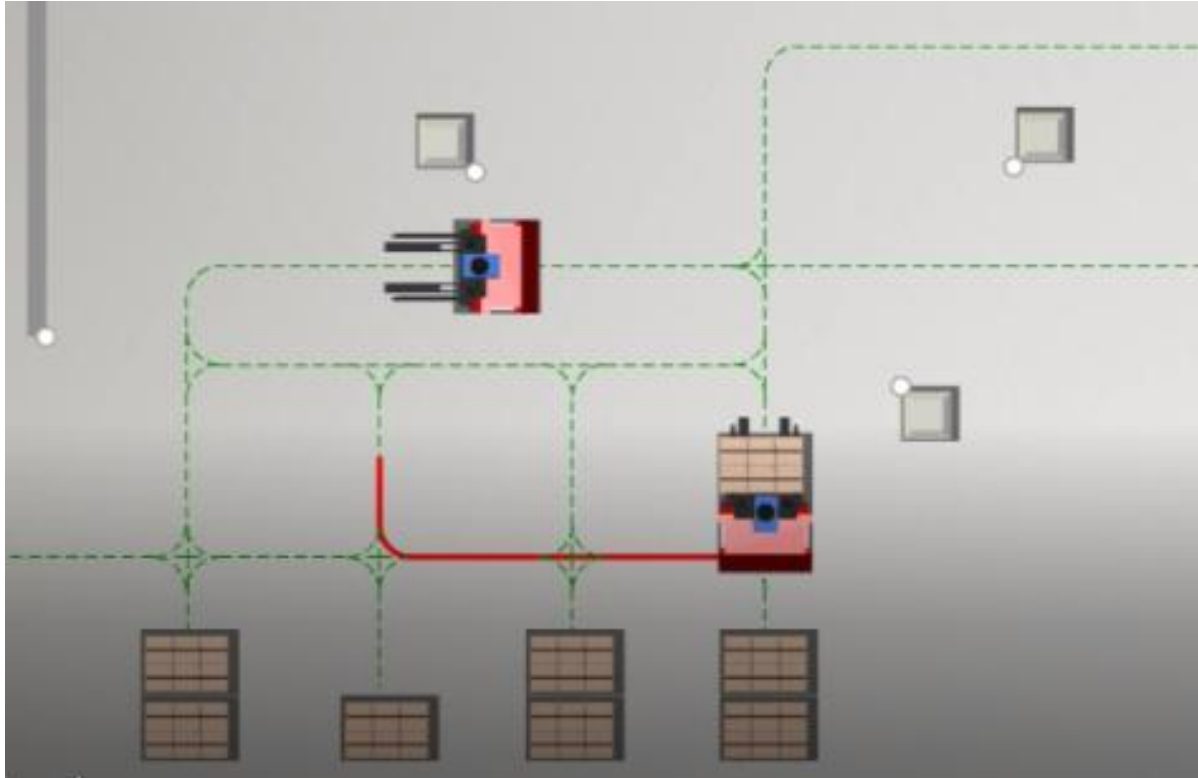
Traffic Management System coordinates fleets of AGV operating in industrial environments.



Host System
Traffic Management
Driveway Layout System
Mission controller

Laser Guided Vehicles:

Coordination of fleets of AGV through Traffic Management system





Safety on AGVs:

Objectives of protection on AGVs :

- ☑ Protect persons from accidents
(for details refer to EN1525/ ISO3691-4)
- ☑ Avoid damage of equipment and goods
- ☑ Minimize downtimes
- ☑ Reduce maintenance costs



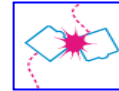
Hazardous area protection



Hazardous point protection



Access safeguarding



Collision prevention

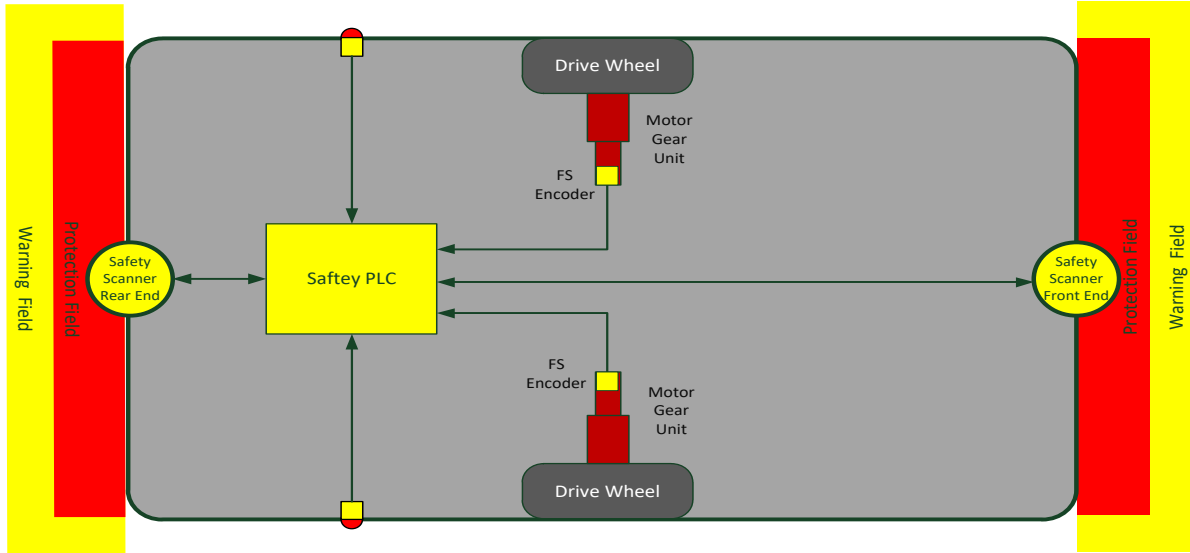
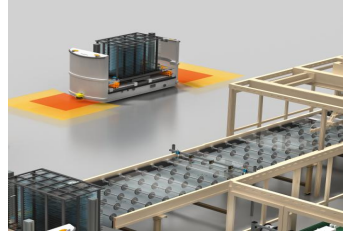


Emergency stop function

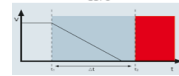


Safety automation

Safety on AGVs: Advanced Safety features



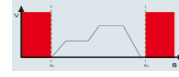
STO - Safe Torque OFF



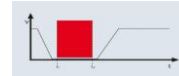
SS1c - Safe Stop according Category 1



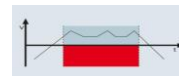
SLS – Safe Limit Speed Maximum Speed Control



SCA- Protection Field Switching



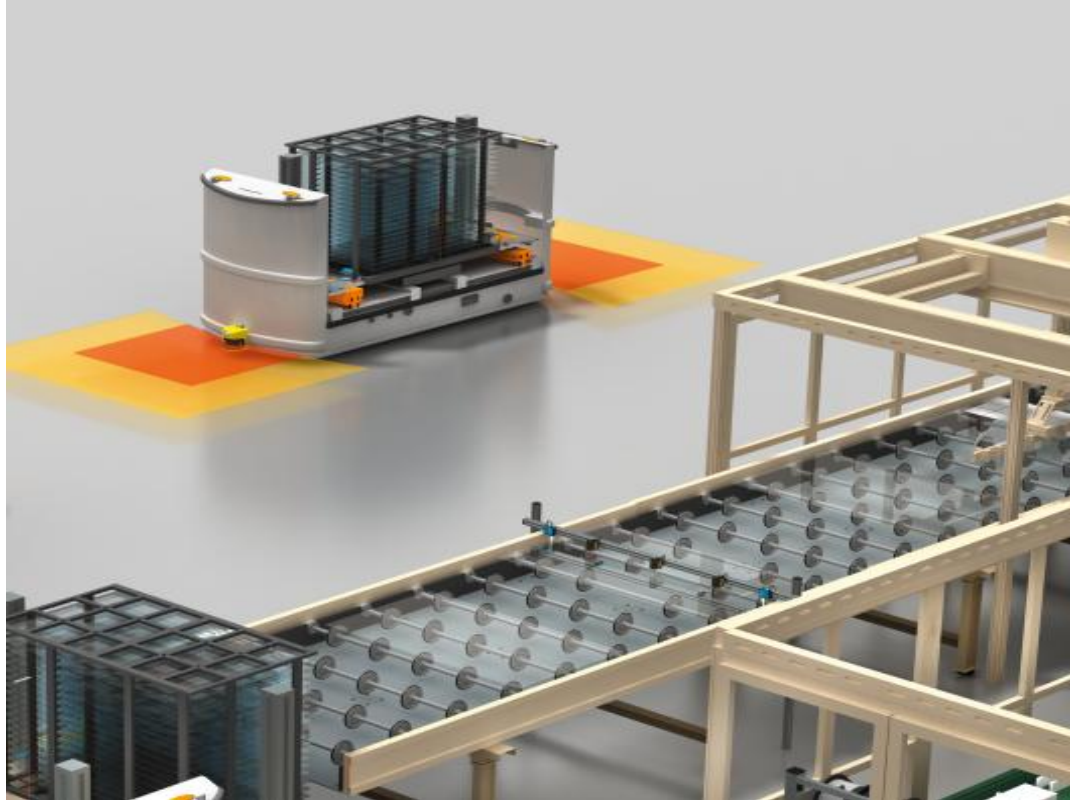
SOS – Safe Operation Speed

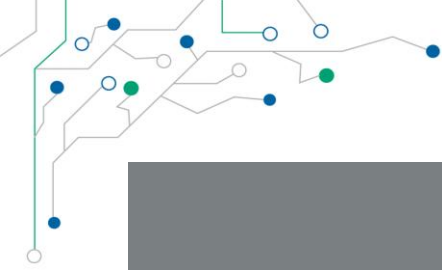


SDI- Safe Direction



Safety on AGVs: Advanced Safety features





Thanks for your attention!